

Haowen Liu

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Education

Southern University of Science and Technology (SUSTech)

Master of Engineering, Electronic Science and Technology
Concentration: Human-robot interaction, Cane Robot, Exoskeleton, ...

Sept. 2021 - June. 2024
Shenzhen, China

Harbin Institute of Technology (HIT)

Bachelor of Engineering, Automation
Concentration: Robot design and control, kinematics, dynamics, ...

Sept. 2017 - June. 2021
Shenzhen, China

Skills

- **Technical:** Programming tools (i.e., C/C++ language, Python, MATLAB), ROS, medical device development, computer-aided design (i.e., SolidWorks), proficiency in embedded system (i.e., STM32), human-robot interaction strategy, biomechanical analysis (e.g., motion capture system, gait analysis)
- **Knowledge:** Robotics, control, mechanical engineering, biomechanical engineering, electronics, system design and development, biomechanics, kinematics, dynamics.

Research Project & Contest

Lower Limb Exoskeleton for Post-Stroke Gait Rehabilitation | SUSTech

Sept. 2021 – May. 2022

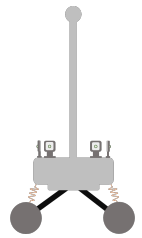
- Updated a wearable cable-driven exoskeleton SEAxo-I to help people regain independent walking ability after stroke and improve their quality of life.
- Achieved clinical validation of SEAxo-II in eight stroke survivors. Proposed personalized assistance strategy enhanced post-stroke participants' walking performance with improvements in gait symmetry, knee flexion, and foot contact angle by **48.4%**, **60%**, and **70.1%**
- Under the guidance of Prof. [Mingming Zhang](#)



Intelligent Cane Robot for Enhancing User's Walking Performance | SUSTech

May. 2022 – Present

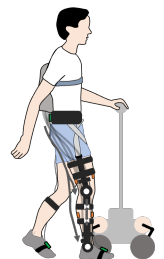
- Developed a new cane-type wheeled robot and proposed a novel human-following control frame with multi-camera fusion. The effectiveness of the method has been validated in outdoor experiments involving six healthy subjects. The results demonstrated that the average tracking error in the X and Y directions was less than **4.1 cm** and **4.4 cm**, respectively.
- Proposed an optimization-based multi-camera configuration to minimize the occlusions by leg during walking.
- considered occlusions of legs and established a linear regression model to compensate for the data loss caused by the occlusions
- Under the guidance of Prof. [Mingming Zhang](#)



Human-Exoskeleton-Cane(HEC) Robot Integrated System | SUSTech

Jan. 2023 – Present

- Updated the cane robot with an active suspension system to enhance its ability to provide support for walking. Additionally, this update has improved its adaptability to different terrains.
- Proposed a biologically inspired human-Exoskeleton-cane interaction rules, which control Exo and cane robot base on use's gait.
- Proposed a multi-camera supervise system which can locate the position of leg, and the average error in the X direction is below **5.4 mm**, the average error in the Y direction is below **2.4 mm**, and the average angle error is below **2.1°**.
- Under the guidance of Prof. [Mingming Zhang](#)



The ABU Asia-Pacific Robot Contest 2020 Suva (Robocon 2020) | HIT

Sept. 2019 - Sept. 2020

- Led the PR group of the WTR Robot Team(HIT), to develop a rugby robot capable of autonomously receiving and kicking the ball.

Publications

- Zhong B⁽¹⁾, Shen M⁽¹⁾, Liu H⁽¹⁾, Zhang M*, et al. "A Cable-driven Exoskeleton with Personalized Assistance Improves the Gait Metrics of People in Subacute Stroke," in *IEEE Transactions on Neural Systems and Rehabilitation Engineering (TNSRE)*, vol. 31, pp. 2560-2569, 2023.
- Liu H⁽¹⁾, Wu F⁽¹⁾, Zhang M*, et al. "Close-Range Human Following Control on a Cane-Type Robot With Multi-Camera Fusion," in *IEEE Robotics and Automation Letters (RAL)*, vol. 8, no. 10, pp. 6443-6450, 2023.

⁽¹⁾co-first author, *response author

Teaching Assistantship

GGC5046 SUSTech Postgraduate English

Fall, 2021

- Established healthy relationships with 24 students by actively supporting them with academic and behavioral guidance.
- Assisted in answering students' questions.
- Graded 240+ homework assignments, quizzes and tests to assist teacher.

AWARDS

- **First Prize** in The ABU Asia-Pacific Robot Contest 2020 Suva (ROBOCON 2020) 2020
- **Third Prize** in The RoboMaster University Championship 2019
- TOPBAND Progressive **Scholarships** 2019
- **Best Technology Prize** in HITsz Robot Cup 2018
- **Third prize** of summer social practice activities 2018
- **Third prize** of winter social practice activities 2018